



FAUNET: A program package for evaluation of fault trees and networks

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Research Establishment Risø

FAUNET: A Program Package
for Evaluation of
Fault Trees and Network

by O. Platz and J. V. Olsen

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FAUNET: A Program Package for Evaluation of
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Research Establishment Riss
Electronics Department

Abstract

A program package for the evaluation of fault trees and networks is described. The package, written in standard Fortran, is primarily designed for use on a minicomputer. Special efforts were therefore made to minimize storage space requirements.

The package contains programs for checking the fault tree input data for logical consistency and for providing various graphical representations of the tree. Furthermore, it contains programs for calculating minimal cut/path sets of the tree. A new technique automatically prunes the fault tree before the minimal set calculation. This pruning has in practice proved to considerably reduce computer time and storage space requirements.

The probability program calculates the availability of the system at various time points from the minimal sets and from failure and repair data for the components. The network program finds all path sets in a directed or undirected network where both links and nodes may fail. The path sets represent the structure function of the network. The minimal cut sets are found by subjecting the structure function to the minimal set programs. The terminal availabilities can be calculated by using the probability program.

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CONTENTS

	Page
Introduction	5
1. Input Data and TREE Programs	7
2. CUT Programs	9
3. Probability Programs, UNA	13
4. Network Program: TIENET	16
References	18
Figures	21

INTRODUCTION

Fault tree analysis (FTA) has become an indispensable tool for the reliability and safety analysis of complex systems. The basic concepts, techniques and applications are described in several papers and reports, e.g. (1 - 3). The state of the art is well represented by the contributions in (4) and (5).

Apart from being a valuable graphical tool for communication, FTA allows a quantitative assessment of system reliability and availability. In this respect, its applications are limited to systems where time sequence is not important, or at least of so little significance that it can be neglected. For systems where time sequence is essential, e.g. for systems where a passive standby is switched in when the main system fails, other techniques such as cause-consequence analysis (6, 7) are more appropriate. Even for systems of this kind, FTA often plays an important role in solving a part of the problem. For the example above, a FTA could be used to obtain the distribution of time to failure for the main system or the unavailability of the standby.

Computer programs for the analytic evaluation of fault trees are by now standard tools in the analysis of complex industrial systems. Many of the programs have been described in the literature (8 - 11). Most of them are written for large computers with ample in-core memory space. In this report we describe how procedures for fault tree evaluation can be implemented on a minicomputer (an 8K PDP8 under OS/8). This is made possible by an new storage-space-saving implementation of the Fussell Vesely (12) algorithm for calculating minimal sets, and by the development of a technique for automatic pruning (or modularization) of fault trees. Although the programs have been developed for use on a minicomputer because of its advantages with regard to interactive analysis and flexibility in handling of data files, they can, with minor modifications, be implemented on any computer that accepts FORTRAN.

The programs of the package fall into four main categories. In section 1 we describe the format of the fault tree input data and the programs under the common label TREE. The first of these programs performs various error checks on the input data. The function of the other programs is to provide graphical fault tree representations from the input data so that the tree can be represented in a form in which it is most easily surveyed.

Section 2 is concerned with the second category of programs under the general heading CUT. The function of these programs is to make a top-down calculation of minimal cut/path sets. One of the programs performs a pruning of the fault tree before it is subjected to the minimal set calculation. For most fault trees, the pruning will much reduce the number and/or the order of the minimal sets, thus making it possible to calculate reliability parameters with an increased accuracy in a shorter time. For the fault tree used as the main example in this report, pruning reduces the number of minimal cut sets from 11934 to 48.

Section 3 describes the UNA programs for reliability and availability calculations from the minimal sets and from failure, repair and test data for the components of the system. The programs accept components with either constant failure probabilities or exponentially distributed failure times. Repair times are either constant or exponentially distributed. Specifications of test intervals are also allowed.

Throughout sections 1 - 3 the fault tree for the Dresden-3 AC emergency power system is used as an example. It is taken from the report by Garrick, Gekler, et al. (13) where it was used to demonstrate a Monte Carlo code. Vesely (14) also used it. As a second example of a calculation of minimal cut sets, we use the fault tree for the High Pressure Injection System (HPIS) from Wash-1400, appendix 2, (15).

Network reliability has been extensively treated in the literature. Although of a general nature, much of the work has been aimed at communication networks. Surveys of work in this field are given in (16) and (17).

Methods for finding all paths between two nodes in a network have been presented by Fu and Yau (18), and Kroft (19). The terminal unavailability, i. e. the probability that the two nodes do not communicate at a given time point, can then be calculated as the probability that all paths between the two nodes are disconnected.

Jensen and Bellmore (20) developed an algorithm for determining all minimal cut sets for the communication between two nodes. The bounding technique of Esary and Proschan (21) was used to provide a lower limit to the terminal availability.

Nelson, Batts and Beadles (22) developed a method for the enumeration of all minimal cut sets between two nodes provided that the path sets were given. From either path or cut sets the terminal availability can be calculated by using the inclusion-exclusion technique (23).

Other methods for the calculation of various network reliability parameters are given in references 24-28.

The network program in the FAUNET package is described in section 4. For a network where links (components) and/or nodes can fail, the program TIENET calculates all paths between two specified nodes. The paths represent the success tree of the network. The Dual of this, the fault tree, is written on an output file. By subjecting the fault tree to a calculation with the CUT programs, all the minimal cut sets of the network can be found. If failure and repair distributions of links and nodes are known, the terminal unavailability can be found by using the UNA programs.

The network program can handle networks with both uni- and bi-directional links.

In section 4 the program is applied to two examples taken from references 20 and 22.

1. INPUT DATA AND TREE PROGRAMS

The format of the input data for the fault trees is illustrated by the data for the fault tree for the Dresden-3 system. The data are shown in fig. 1. They were obtained from appendix E in (13) where the tree structure was given in terms of logical FORTRAN statements. The first line in the file contains the name of the fault tree (FORTRAN format A6). Each of the following lines defines a gate in the tree in the form: gate type - gate number - number of gate inputs - list of gate inputs. The FORTRAN format is A1, 20I4. The gate type is specified as + or O for an OR gate, and as X or A for an AND gate. Events are indexed from 1 to 999 and gates are indexed from 1000 to 2000. The order in which the gates are defined in the file is immaterial. The \$ sign in the last line denotes the end of the file.

For convenience in writing input files, the data can be written in free format with commas as delimiters. A program, FREE, then reads the input data in free format and produces an output file of data for either the Primal or the Dual tree in fixed format. The Dual tree is obtained from the Primal by converting AND gates to OR gates and vice versa, and by letting the basic events denote their logical inverses.

The TREE package consists of 4 programs:

TREECH, the error checking program, reads the input data in fixed format and lists the number of OR and AND gates and the number of basic events. It also produces a list of basic events and gates together with the number of times they occur in the tree. It checks the tree to see if it is connected and to see if there are multiple definitions of a gate. It furthermore checks the tree for loops. Finally, it calculates the number of BICS

(Boolean Indicated Cut Sets (2)) and the maximum length of these for each gate. Apart from checking the data for errors, the functions performed by TREECH are helpful in assessing the size of the problem in the following calculation of minimal cut sets. As an option, the functions of TREECH can be performed on the Dual tree instead of the Primal. The information obtained is then pertinent to the path sets (tie sets) of the fault tree.

Figures 2 and 3, respectively, show the output produced by TREECH for the Primal and the Dual versions of the fault tree Dresden-3. The asterisks in the last line of fig. 2 just indicate that the number of BICS exceeded the format of the output statement. The number will be about $33 \cdot 10^{12}$.

TREEIN, the input module for the graphical programs, accepts input data in fixed format. The program asks for a specification of a top event (Gate). As a default it takes the gate in the second line of the input data (gate 1060 in fig. 1). With the selected top event as an ancestor, the program orders gates and events according to the generation in which they occur, and it allocates each component (gates and events) an initial set of coordinates for its position in the graph.

The structural description is stored in COMMON. Overflow data are left on a file for processing in a later pass.

TREEBA, the balancing module, accepts the tree description in COMMON from TREEIN and calculates new x-coordinates for positioning gates and events to give, as far as possible, a well balanced picture.

Initially, all components are placed as far to the left as possible. The tree is squeezed along the left edge of the picture. The balancing is an iterative process, moving the components from their initial left positions to the right on the plane. In a series of upwards and downwards scans the algorithm tries to establish a position of any gate name (output) and the inputs to the gate so that the output is placed above the central input, in the case of an odd number of inputs, or in the middle of the two central inputs in the case of an even number of inputs. The inputs are moved in the down-going scan, and the outputs in the upgoing. The components do not move more than allowed by their neighbours. Only movements toward the right are permitted.

This process is repeated until no further movements occur. The result is still kept in COMMON while the output module is called.

TREEOU, the output module, draws the structure on the lineprinter, specifying gates by type, number and connection to inputs.

If there are more data than allowed on one sheet, the control is given back to TREEIN for another pass to evaluate the next part of the tree from the data stored in the overflow file.

If a gate occurs more than once in the input data, the subtree corresponding to this gate is developed the first time it appears as input (i. e. as near to the top gate as possible). The next time it occurs, e. g. in another branch or in a later generation, it is not expanded into its subtree but only referred to by the gate number. It is, nevertheless, possible to force the subtree corresponding to the gate to be "pressed" downwards in the tree by adding an extra line in the input data above the actual gate definition. This line should contain the gate number with no inputs. As gate type an \wedge may be used to indicate that it is a subtree.

If a gate is "pressed" out of the tree in this way it will be processed separately and drawn on a separate sheet (e. g. gate 1055 in fig. 4).

2. CUT PROGRAMS

The package consists of 7 programs:

CUTSET	Input and gate contraction
CUTUP	Factoring, or modularisation, (bottom-up analysis)
CUTGO	Evaluation of minimal cut sets
CUTOFL	Overflow handling
CUTRED	Inter-block reduction
CUTOUT	Result calculation
CUTEV	Expansion of factorized minimal sets (optional)

Each of the first 6 programs calls the next in sequence by CHAIN.

CUTSET reads the input data in fixed format and asks for the highest order of sets wanted in the result together with a specification of the top event. As a default it uses the gate defined in the second line of the input file. The user may specify whether he requires a cut set or a tie set (path set) calculation of the fault tree. The program then contracts subsequent gates of the same type in the tree into a single gate, so that the tree structure becomes an alternating sequence of OR and AND gates. The data that are stored in COMMON are now ready for the next step:

CUTUP performs a bottom-up analysis by identifying primitive factors, i. e. a pair of basic events always occurring together in the same types of gate. Such a pair is replaced by a dummy event, here called a "complex event", while a description of this factor in terms of its type and inputs is written at the top of the result file. If, in the next pass, two complex events (or a complex event and a basic event) always appear as a pair in the same types of gate, they are combined into a new complex event and so on. This process continues until no more pairs are found. For each pass CUTUP prints "FACTORIZE". Finally CUTUP calls:

CUTGO, which identifies itself by the message "EVALUATE". CUTGO performs the actual evaluation of the cut sets/path sets. The evaluation is based on the Fussell Veseley algorithm (12). A description of the algorithm together with an application to a simple fault tree is also contained in (23).

All operations in CUTGO are performed in a single one-dimensional array placed in COMMON. The first part of the array contains the description of the factorized fault tree. Each gate is specified by type and inputs (gates, basic and/or complex events). For each gate there is a pointer to the array element where the information about the next gate begins. The remaining part of the array is reserved for cut set expansions. From now on this part is called the buffer.

The evaluation starts by replacing the top event with a list of its inputs. The list is placed in the buffer preceded by a pointer to indicate its length. The program then looks up the first gate in the buffer and expands it according to the Fussell Veseley algorithm. An AND gate will be expanded into a single and, in most cases, longer list of inputs. An OR gate will usually give rise to several new lists of the same length as the old one. The resulting lists are added to the lists already in the buffer together with pointers and the array elements which have been occupied by the old list are set free.

Every time the buffer is filled, i. e. no more free space is available at the end of the buffer, CUTGO performs a garbage collection to retrieve the free elements.

When no more free space is available, CUTGO enters the minimization phase. Here all cut sets, whether fully evaluated or not, are sorted according to size and compared for removal of all redundant sets. The message "MINIMIZE" is printed.

If some cut sets are removed, the program goes back to garbage collection followed by further expansions. If not, the overflow handler is called.

If the evaluation is finished (no cut sets contain gates as inputs) the overflow handler is called too.

CUTOFL, the overflow handler, starts with the message "OVERFLOW". This module extracts all partially evaluated sets as well as sets of order higher than that specified by the user as maximum. The sets are extracted from the array in COMMON and added to an overflow file on backing store.

The remaining sets are then added to the result file.

Finally, if there are any overflow data of lower order than the maximal, they are loaded into the buffer and control is given back to CUTGO to perform further evaluations.

If there are no more overflow data, or all the overflow data are of higher order than that specified as maximum, and all cut sets in the buffer have been fully evaluated, the control is given to:

CUTRED, which performs an inter-block minimization between the blocks in the result file that have been produced by several passes between CUTGO and CUTOFL. The message "REDUCE" is printed. CUTRED finally sorts all minimal sets in the result file according to order and input events.

The result file is a file containing:

- 1) calculation type (CUTSET/TIESET) and fault tree name,
- 2) a list of factors (definitions of complex events),
- 3) all minimal cut sets/tie sets found with order less than or equal to the maximal required.

CUTOUT is the final program that scans the result file and calculates the number of minimal sets of any order for the factorized tree, as well as the number of minimal sets for the original tree.

CUTEV, an independent program, may be called optionally. It accepts the result file as input, and as output it produces a list of the minimal sets for the original tree.

Examples

Example 1, Dresden-3

Figure 5 shows the questions and the messages printed by the computer and the answers typed by the operator under the execution of the Dresden-3 fault tree. The first line is a run command to the operating system. In the next lines the operator specifies that he requires a cut set calculation on the input data existing as a disk (DSK) file DRES3. He makes certain that the

cut sets are calculated to any order by typing 999 as answer to the question about the highest order wanted. As a default, the computer selects gate 1060 as top event.

After having made several passes through minimization, overflow and evaluate stages, the output module CUTOUT prints the number and the order of the minimal cut sets for the factorized tree and for the original tree. For the Dresden-3 fault tree the modularization technique causes a reduction of the total number of minimal cut sets from 11934 to 48.

The result file is listed in fig. 6. The first line contains the name of the fault tree together with a specification of the type (cut/tie) of the sets. The following lines contain the definitions of the complex events, which are indexed from 999 and downwards; -1 indicates an OR gate, -2 an AND gate. The second line in the file thus shows that complex event no. 999 is an OR gate with the basic events 50 and 51 as inputs.

The 48 minimal cut sets follow after a mark (-959 here). The first number in each line is just an indication of the number of data in the line. If the complex events in these cut sets were expanded (e.g. by CUTEV) according to their definitions, the 11934 minimal sets for the original tree would be obtained.

Figures 7-8 show the calculation of the minimal tie sets for the Dresden-3 fault tree. The complex events in fig. 8 are, of course, identical to those in fig. 6, except for the fact that OR gates in the Primal tree are converted to AND gates in the Dual tree. The total number of path sets are 8 both for the factorized tree and for the original tree, but they are of considerably lower order in the factorized tree.

Example 2, HPIS

Figures 9-13 show the input data, the outputs of the checking program, and the minimal cut set programs for the fault tree of the High Pressure Injection System taken from appendix 2 of Wash-1400. The 8179 minimal cut sets of the original tree are reduced to 52 minimal sets in the factorized tree.

It was not possible to calculate all the minimal path sets of the HPIS fault tree. As seen from fig. 11, there are 248832 BICS (or rather BIPS, Boolean Indicated Path Sets) of maximal length 174. The number, and size, of the actual minimal path sets, even for the factorized tree, exceeded the capacity of the PDP8 minicomputer.

3. PROBABILITY PROGRAMS, UNA

The UNA programs calculate system unavailability from the minimal sets of the factorized tree when failure, repair and test data are given for the components of the system. The components are assumed to be statistically independent.

In their present form the programs accept exponentially distributed failure times and repair times that are either constant or exponentially distributed. They also accept constant failure probabilities for components with a fixed probability of failure per demand. For the purpose of treating components where failures are only detected at tests, the programs furthermore allow the specification of constant test intervals.

In order to minimize the requirements to core storage space, the programs perform a dynamic allocation of storage space similar to that used in the CUT programs. Only a single one-dimensional array is used. In the following the array that is placed in COMMON is called the internal buffer.

UNAVA1, the main program, administrates the subroutine calls. It first calls:

UNAIN1, which reads the basic failure, repair and test data from the input data file. The information is stored in the internal buffer. The program then reads the complex events (i. e. type, number and inputs) from the cut/tie set file, the result file from the CUT programs. This information is also placed in the internal buffer. Finally, the program reads the minimal sets from the same file and stores them in a direct access disk file, the external buffer. The control is then given back to the main program which asks the operator to specify the time points at which he requires the calculations performed and the number of inclusion-exclusion terms, he needs in the calculation of the system unavailability. The main program then calls:

UNASU1, which calculates the unavailability of the components from their failure data. If a component has an exponential failure distribution with failure rate λ and exponential repair distribution with mean repair time r , the unavailability as a function of time t is given by the well known expression

$$u(t) = \frac{\lambda}{\lambda + 1/r} (1 - e^{-(\lambda + 1/r)t}) ,$$

when the component was operating at time 0.

If the component has an exponential failure distribution with failure rate λ and constant repair time r the unavailability is given by (29)

$$u(t) = 1 - \sum_{j=0}^{[t/r]} \frac{\lambda^j (t-rj)^j e^{-\lambda(t-rj)}}{j!},$$

where $[t/r]$ denotes the greatest integer contained in t/r .

For a component with an exponential failure distribution $1 - e^{-\lambda t}$ and constant repair time r , and subjected to periodic tests with a test interval T , so that failures are revealed and repaired at tests only, the point unavailability is easily found to be given by the expression:

$$u(t) = \begin{cases} 1 - e^{-\lambda t} & \text{for } t < T \\ (1-a)(1 - e^{-\lambda t'}) + a & \text{for } t \geq T \text{ and } t' \leq r \\ (1-a)(1 - e^{-\lambda t'}) + a(1 - e^{-\lambda(t'-r)}) & \text{for } t \geq T \text{ and } t' > r \end{cases}$$

here $t' = t \text{ modulo } T$, and $a = 1 - e^{-\lambda T}$. It is assumed that $r \leq T$.

After having calculated the unavailabilities of all the components the program stores the results in the internal buffer and the next subroutine is called.

UNACP1 calculates the probabilities of the complex events from the probabilities of the basic events, i. e. the unavailabilities of the components. If the complex event 1 is an OR gate with input events (basic or complex) m and n , the probability p_1 of the complex event is given by

$$p_1 = p_m + p_n - p_m \cdot p_n,$$

where p_m and p_n are the probabilities of the statistically independent input events. For an AND gate the corresponding expression is given by

$$p_1 = p_m \cdot p_n.$$

Having calculated the probabilities of all complex events, the program stores the results in the internal buffer and the main program calls:

UNAFI1, which performs the final calculation of system unavailability from the minimal sets of the factorized tree and from the probabilities of basic and complex events.

The program calculates the probability of the union of the minimal sets by using the inclusion-exclusion technique(23). In its present form the program is able to include the three first terms in the expansion.

Example, Dresden-3

The failure data for the Dresden-3 fault tree are taken from table 2.10 of the Holms and Narver report(13). Figure 14 shows the data written as a free format input file for the UNA programs. Each line in the file consists of component number, calculation type, number of succeeding data inputs, failure data, mean repair time and test interval.

Generally, calculation type 1 denotes a constant failure probability; type 2, exponential failure and repair distributions; while types 3 and 4 denote exponential failure distribution and constant repair time. In the case of type 4, failures are only detected at tests.

Failure data are either constant probabilities (calculation type = 1), or failure rates. In both cases the program multiplies the number in the input file by 10^{-6} .

In the HN report, the Dresden-3 fault tree was run with the SAFTE Monte Carlo simulation code. The failure rates given for the components were used, but the components were assumed to be non-repairable. Vesely(14) also used this fault tree to illustrate the KITT computer codes. Because of the amount of cut sets in the fault tree, Vesely based his calculations on the minimal path sets. A KITT-1 run was made with the 8 minimal path sets found. The failure rates used were those given in the HN report. Vesely also made a KITT-2 run in order to obtain results for the repairable system. The components were assumed to have constant repair times, the average repair times given in the HN report were used and the standard deviations associated with the actual normal repair distributions were ignored. Vesely obtained the exact answer by using all inclusion-exclusion terms for the minimal path sets. In general, it is necessary to use all terms in a probability calculation based on minimal path sets in order to obtain sufficient accuracy when the component failure probabilities are small.

Figures 15-16 show the results of calculations with the UNA programs for the same cases as considered by Vesely. In contrast to his calculations, the calculations here were based on minimal cut sets, i. e. the 48 minimal cut sets of the reduced fault tree. Two inclusion-exclusion terms were calculated. The terms provide upper and lower bounds to the exact probabilities. As seen from the figures, the first term alone gives a sufficiently accurate answer for most of the time range considered.

To facilitate comparison with the results from (13) and (14), figure 15 shows a calculation for the non-repairable case with time points corresponding to an integer number of weeks. The results are in good agreement with the graphs in (13) and (14).

For the repairable case, the results are given in figure 16 for the time points corresponding to those calculated in (14). The results in figure 16 differ slightly in the second decimal point from those in (14). The error is presumably due to the small word length in the PDP8 minicomputer (mantissa = 24 bits).

4. NETWORK PROGRAM: TIENET

For a network with bi- or uni-directional links (components) the program calculates all paths between two nodes specified by the user. The paths represent the "success" tree of the network. The Dual of this, the fault tree, is written on an output file. The data are acceptable in this form as input data for the CUT programs.

The algorithm used here is identical in principle to that given by Kroft(19), but the implementation differs. Kroft's algorithm was based on a description of the nodes only. We are interested in obtaining the fault tree of the system in terms of its representation by minimal cut sets where the basic events represent failures of components or nodes, or both. It is therefore necessary to use a description of the network in terms of its links as well as of its nodes.

Example 2 in reference 22 is used to illustrate the performance of TIENET. The network is shown in figure 17. As seen from the figure, all links are uni-directional. The component numbers are those given in 22. The nodes have been given the numbers shown in the figure.

The input data file is shown in figure 18. Each line in the file consists of: component number - input node - output node. The component numbers in this file are all negative, which signifies that the links are uni-directional. Bi-directional links are written with positive component numbers in the input data. TIENET then replaces each bi-directional link with its two uni-directional equivalents.

Two internal lists, a component list and a node list, figure 19, are made by TIENET from the input data. Both lists are placed in the same one-dimensional array. The component list is a list of component descriptions arranged according to component number. Each component description contains: component number - input node - output node. In the node

list each node is described in terms of the next components that can be reached from it by a flow originating in the node. Each node description consists of: a pointer L to the first element in the next node description - node number - N, the total number of succeeding component pointers - an element with a pointer (IPREV) to the previous node encountered in the instant path search - a pointer (IFLAG) pointing towards one of the succeeding component pointers, the one representing the component under investigation in the instant path search (IFLAG \neq 0 indicates that the node has been encountered previously in the path search) - and a series of N component pointers (each pointer pointing towards the corresponding component description in the component list).

A flowchart of the search algorithm used in TIENET is given in figure 20. The algorithm searches out all paths between the start node and the end node, avoiding paths with loops.

The output file from TIENET is shown in figure 21. If the output-file is subjected to a "cut set" calculation by the CUT programs the minimal cut sets of the network are found and written out in standard form, figure 22. If the file is subjected to a "tie set" calculation, the minimal path sets of the network are written out, figure 23. The expanded minimal cut and path sets are identical to those found in (22).

As a second example we use the network given in figure 1 of reference 20. It is reproduced here in figure 24. The input data file is shown in figure 25.

Figure 26 shows three runs of TIENET for the paths between nodes 1 and 8; one for nodes only, one for components only, and one for both nodes and components. When the three output files are used as inputs to the CUT programs, the results in figures 27 - 29 are obtained. The minimal cut sets for components only are identical to those found in (20). The number of minimal cut sets differs in the three cases because of the difference in vulnerability of the network to node failures and to link failures.

The number of minimal path sets is, of course, the same in the three cases. The only difference lies in the way in which they are specified. The path sets for components only are shown in figure 30.

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```

DRESD3
X1060 210591058
X1059 210451053
+1053 210511052
+1051 21050 55
+1050 210481049
+1049 2 53 54
+1048 2 521047
+1047 210461057
+1046 2 51 50
+1052 2 56 57
+1045 210431044
+1044 2 48 49
+1043 2 471042
+1042 210401041
+1041 2 45 46
+1040 2 441039
+1039 210381055
+1038 2 42 43
X1058 210551057
X1057 3103210341037
+1037 210251036
+1036 2 40 41
+1034 210201033
+1033 2 36 37
+1032 210311056
X1056 210281030
+1028 210171027
+1027 2 30 31
+1017 2 181015
+1030 210091029
+1029 2 32 33
+1031 2 34 35
X1055 3101910221026
+1026 210231025
+1025 3 2910351024
+1035 2 38 39
+1024 2 27 28
+1023 2 25 26
+1022 210201021
+1021 2 21 22
+1020 2 23 24
+1019 210181054
+1018 2 19 20
X1054 210111016
+1011 2 121010
+1010 2 111009
+1009 2 101008
+1008 210061007
+1007 2 8 9
+1006 2 2 7
+1016 2 171015
+1015 2 161014
+1014 210121013
+1013 2 14 15
+1012 2 131005
+1005 210031004
+1004 2 5 6
+1003 210011002
+1002 2 3 4
+1001 2 1 2
$

```

Fig. 1. Input data for the Dresden-3 fault tree.

CHECK OF INPUT DATA FOR : DRESO3 (PRIMAL)

GATE 1060 OCCURS ON LEFT SIDE BUT NOT ON RIGHT

NO OF DIFFERENT OR - GATES = 53
NO OF DIFFERENT AND - GATES = 7

TOTAL NO OF DIFFERENT GATES = 60
NO OF DIFFERENT EVENTS = 57

EVENTS	1	2	3	4	5	6	7	8	9	10	11	12
REPLICATION	4	8	4	4	4	4	4	4	4	4	2	2
EVENTS	13	14	15	16	17	18	19	20	21	22	23	24
REPLICATION	4	4	4	4	2	2	2	2	2	2	4	4
EVENTS	25	26	27	28	29	30	31	32	33	34	35	36
REPLICATION	2	2	4	4	4	2	2	2	2	2	2	2
EVENTS	37	38	39	40	41	42	43	44	45	46	47	48
REPLICATION	2	4	4	2	2	1	1	1	1	1	1	1
EVENTS	49	50	51	52	53	54	55	56	57			
REPLICATION	1	1	1	1	1	1	1	1	1			

GATE	BICS	MAX LENGTH	REPLICATION
1001	2	1	1
1002	2	1	1
1003	4	1	1
1004	2	1	1
1005	6	1	1
1006	2	1	1
1007	2	1	1
1008	4	1	1
1009	5	1	2
1010	6	1	1
1011	7	1	1
1012	7	1	1
1013	2	1	1
1014	9	1	1
1015	10	1	2
1016	11	1	1
1017	11	1	1
1018	2	1	1
1019	79	2	1
1020	2	1	2
1021	2	1	1
1022	4	1	1
1023	2	1	1

GATE	BICS	MAX LENGTH	REPLICATION
1024	2	1	1
1025	3	1	2
1026	7	1	1
1027	2	1	1
1028	13	1	1
1029	2	1	1
1030	7	1	1
1031	2	1	1
1032	93	2	1
1033	2	1	1
1034	4	1	1
1035	2	1	1
1036	2	1	1
1037	7	1	1
1038	2	1	1
1039	2214	4	1
1040	2215	4	1
1041	2	1	1
1042	2217	4	1
1043	2218	4	1
1044	2	1	1
1045	2220	4	1
1046	2	1	1
1047	2606	4	1
1048	2607	4	1
1049	2	1	1
1050	2609	4	1
1051	2610	4	1
1052	2	1	1
1053	2612	4	1
1054	77	2	1
1055	2212	4	2
1056	91	2	1
1057	2604	4	2
1058	5760049	8	1
1059	5798642	8	1
1060*****		16	

Fig. 2. TREECH output for the Dresden-3 fault tree.

CHECK OF INPUT DATA FOR DRESD3 (DUAL)

GATE 1060 OCCURS ON LEFT SIDE BUT NOT ON RIGHT

NO OF DIFFERENT OR - GATES = 7

NO OF DIFFERENT AND - GATES = 53

TOTAL NO OF DIFFERENT GATES = 60

NO OF DIFFERENT EVENTS = 57

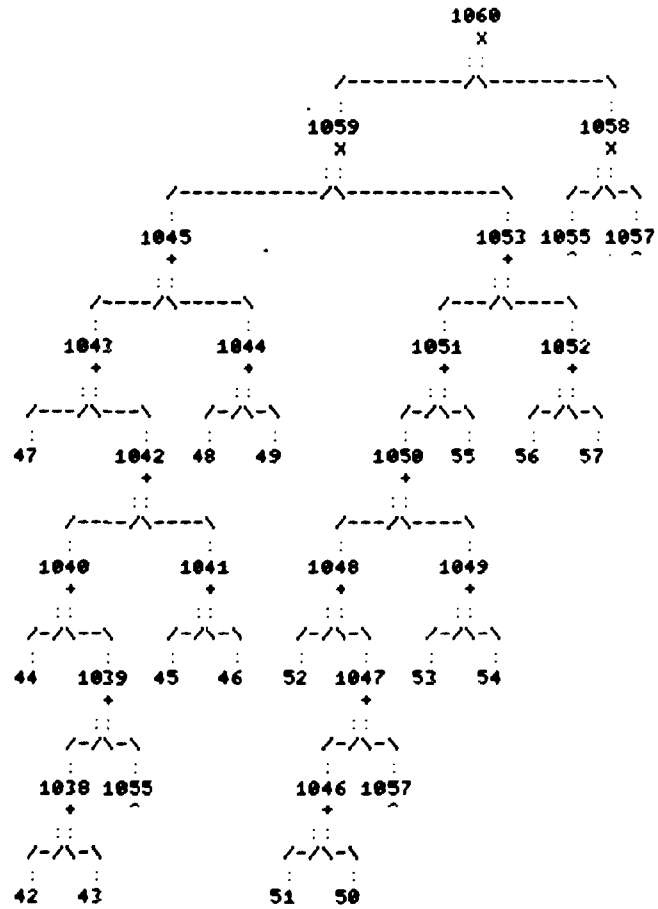
EVENTS	1	2	3	4	5	6	7	8	9	10	11	12
REPLICATION	4	0	4	4	4	4	4	4	4	4	2	2
EVENTS	13	14	15	16	17	18	19	20	21	22	23	24
REPLICATION	4	4	4	4	2	2	2	2	2	2	4	4
EVENTS	25	26	27	28	29	30	31	32	33	34	35	36
REPLICATION	2	2	4	4	4	2	2	2	2	2	2	2
EVENTS	37	38	39	40	41	42	43	44	45	46	47	48
REPLICATION	2	4	4	2	2	1	1	1	1	1	1	1
EVENTS	49	50	51	52	53	54	55	56	57			
REPLICATION	1	1	1	1	1	1	1	1	1			

GATE	BICS	MAX LENGTH	REPLICATION
1001	1	2	1
1002	1	2	1
1003	1	4	1
1004	1	2	1
1005	1	6	1
1006	1	2	1
1007	1	2	1
1008	1	4	1
1009	1	5	2
1010	1	6	1
1011	1	7	1
1012	1	7	1
1013	1	2	1
1014	1	9	1
1015	1	10	2
1016	1	11	1
1017	1	11	1
1018	1	2	1
1019	2	13	1
1020	1	2	2
1021	1	2	1
1022	1	4	1
1023	1	2	1

GATE	BICS	MAX LENGTH	REPLICATION
1024	1	2	1
1025	1	5	2
1026	1	7	1
1027	1	2	1
1028	1	13	1
1029	1	2	1
1030	1	7	1
1031	1	2	1
1032	2	15	1
1033	1	2	1
1034	1	4	1
1035	1	2	1
1036	1	2	1
1037	1	7	1
1038	1	2	1
1039	4	15	1
1040	4	16	1
1041	1	2	1
1042	4	10	1
1043	4	19	1
1044	1	2	1
1045	4	21	1
1046	1	2	1
1047	4	17	1
1048	4	10	1
1049	1	2	1
1050	4	20	1
1051	4	21	1
1052	1	2	1
1053	4	23	1
1054	2	11	1
1055	4	13	2
1056	2	13	1
1057	4	15	2
1058	8	15	1
1059	0	23	1
1060	16	23	

Fig. 3. TREECH output for the Dual of the Dresden-3 fault tree.

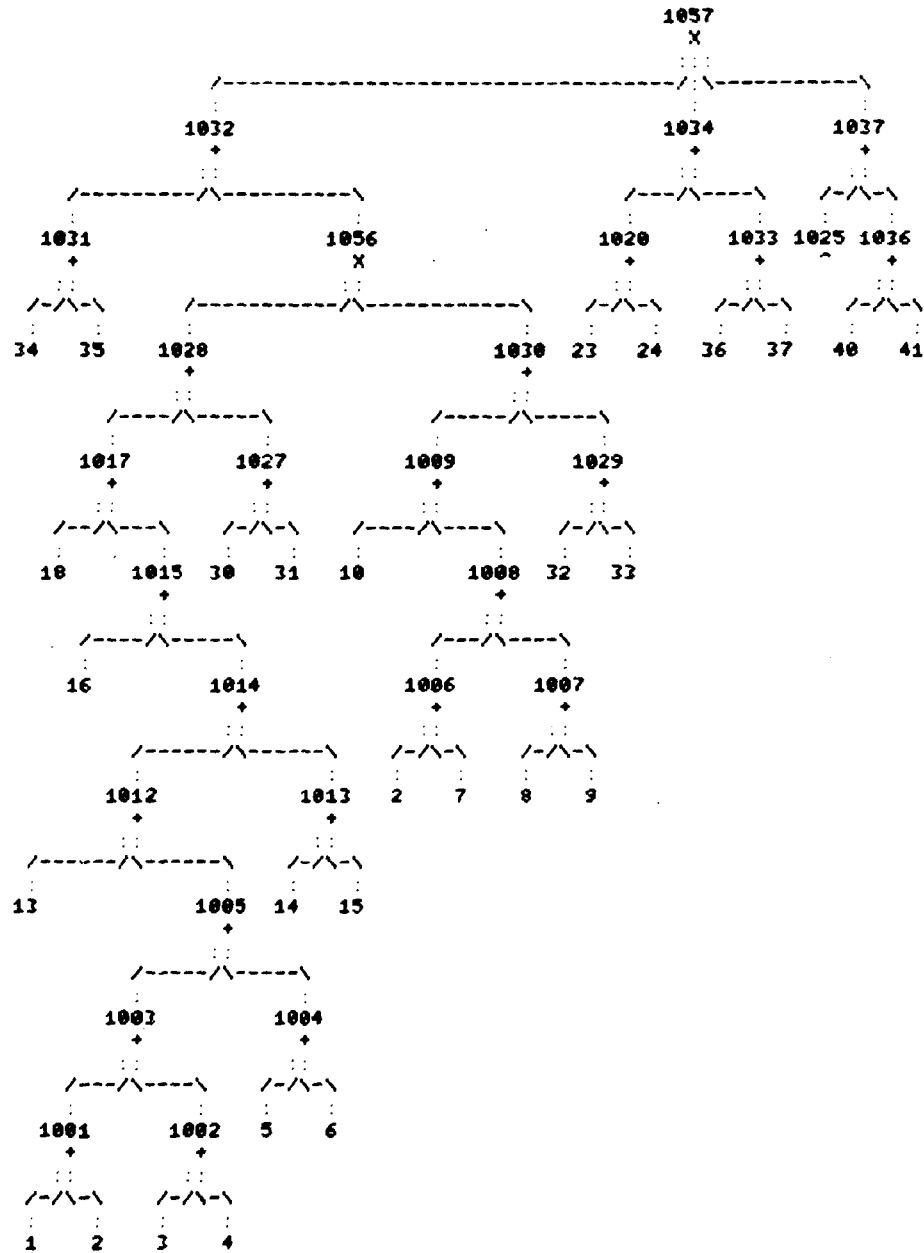
1 SYSTEM: DRESD3 PART: 1



1

Fig. 4. Dresden-3 fault tree.

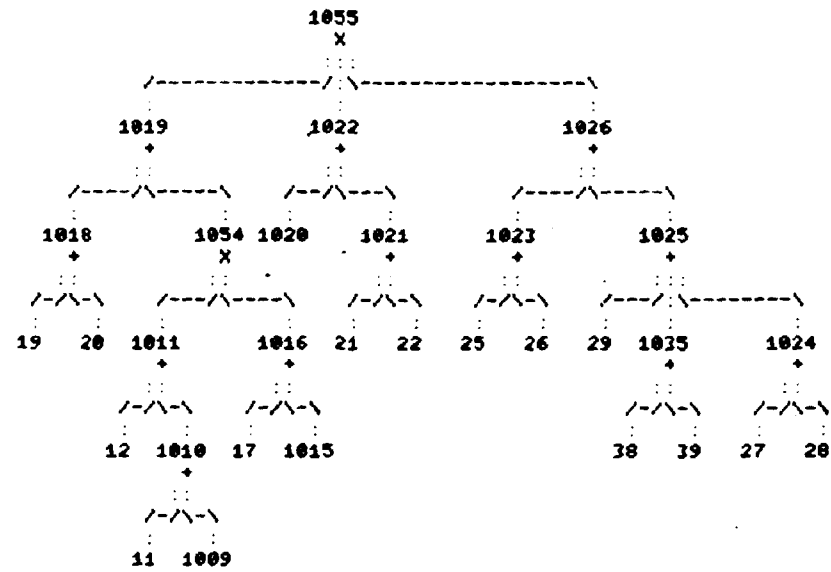
1 SYSTEM: DRESO3 PART: 2



1

Fig. 4. Dredson-3 fault tree.

1 SYSTEM: DRESO3 PART: 3



1

Fig. 4. Dresden-3 fault tree.

```

R CUTSET
CUTSET OR TIESET: CUTSET
CUTSET OF:
FILE DSK0: DRES03
SYSTEM: DRES03
HIGHEST ORDER WANTED = 999
TOP GATE:
GATE: 1060 SELECTED AS TOP
FACTORIZE
EVALUATE
MINIMIZE
MINIMIZE
MINIMIZE
MINIMIZE
MINIMIZE
MINIMIZE
MINIMIZE
MINIMIZE
MINIMIZE
MINIMIZE
OVERFLOW
EVALUATE
MINIMIZE
MINIMIZE
MINIMIZE
OVERFLOW
EVALUATE
MINIMIZE
MINIMIZE
MINIMIZE
OVERFLOW
EVALUATE
MINIMIZE
MINIMIZE
MINIMIZE
OVERFLOW
EVALUATE
MINIMIZE
MINIMIZE
MINIMIZE
OVERFLOW
EVALUATE
MINIMIZE
MINIMIZE
MINIMIZE
OVERFLOW
REDUCE
OUTPUT

```

RESULT OF DRES03

REDUCED CUTSET:

```

1. SETS OF ORDER 3
4. SETS OF ORDER 4
13. SETS OF ORDER 5
19. SETS OF ORDER 6
10. SETS OF ORDER 7
1. SETS OF ORDER 8
-----

```

48.

EVALUATED CUTSET:

```

10. SETS OF ORDER 3
428. SETS OF ORDER 4
2816. SETS OF ORDER 5
5464. SETS OF ORDER 6
3024. SETS OF ORDER 7
192. SETS OF ORDER 8
-----

```

11934.

Fig. 5 Teletype output during calculation of minimal cut sets of the Dresden-3 fault tree.

CUTSET OF DRESD3

4	-1	999	50	51
4	-1	998	42	43
4	-1	997	34	35
4	-1	996	27	28
4	-1	995	23	24
4	-1	994	19	20
4	-1	993	7	8
4	-1	992	1	3
4	-1	991	52	53
4	-1	990	44	45
4	-1	989	29	30
4	-1	988	16	17
4	-1	987	21	22
4	-1	986	9	10
4	-1	985	4	5
4	-1	984	54	55
4	-1	983	46	47
4	-1	982	39	989
4	-1	981	32	33
4	-1	980	11	12
4	-1	979	6	13
4	-1	978	56	57
4	-1	977	48	49
4	-1	976	40	41
4	-1	975	25	26
4	-1	974	986	993
4	-1	973	14	15
4	-1	972	978	984
4	-1	971	977	981
4	-1	970	982	996
4	-1	969	16	973
4	-1	968	972	991
4	-1	967	971	990
4	-1	966	969	979
4	-1	965	968	999
4	-1	964	967	998
4	-1	963	966	985
4	-1	962	963	992
4	-1	961	18	30
4	-1	960	31	961
-959				
3	2	970	995	
4	2	970	987	988
4	2	975	976	995
4	962	970	974	995
4	970	994	995	997
5	2	975	976	987 988
5	17	960	970	974 995
5	17	970	974	995 997
5	17	970	980	995 997
5	960	970	974	994 995
5	960	970	981	994 995

5	962	970	974	987	988
5	962	970	980	981	995
5	962	970	980	995	997
5	962	970	981	994	995
5	962	974	975	976	995
5	970	987	988	994	997
5	975	976	994	995	997
6	17	960	970	974	987 988
6	17	960	970	980	981 995
6	17	960	974	975	976 995
6	17	970	974	987	988 997
6	17	970	980	987	988 997
6	17	974	975	976	995 997
6	17	975	976	980	995 997
6	960	970	974	987	988 994
6	960	970	981	987	988 994
6	960	974	975	976	994 995
6	960	975	976	981	994 995
6	962	970	980	981	987 988
6	962	970	980	987	988 997
6	962	970	981	987	988 994
6	962	974	975	976	987 988
6	962	975	976	980	981 995
6	962	975	976	980	995 997
6	962	975	976	981	994 995
6	975	976	987	988	994 997
7	17	960	970	980	981 987 988
7	17	960	974	975	976 987 988
7	17	960	975	976	980 981 995
7	17	974	975	976	987 988 997
7	17	975	976	980	987 988 997
7	960	974	975	976	987 988 994
7	960	975	976	981	987 988 994
7	962	975	976	980	981 987 988
7	962	975	976	980	987 988 997
7	962	975	976	981	987 988 994
8	17	960	975	976	986 981 987 988

Fig. 6. Result file for the Dresden-3 fault tree.

```

R CUTSET
CUTSET OR TIESET: TIESET
TIESET OF DSK
FILE DSK0 DRES03
SYSTEM: DRES03
HIGHEST ORDER WANTED = 999
TOP GATE
GATE 1060 SELECTED AS TOP
FACTORIZE
EVALUATE
MINIMIZE
MINIMIZE
OVERFLOW
REDUCE
OUTPUT

RESULT OF DRES03

REDUCED TIESET
  4 SETS OF ORDER 2
  4 SETS OF ORDER 4
-----
  8

EVALUATED TIESET:
  2 SETS OF ORDER 4
  2 SETS OF ORDER 7
  2 SETS OF ORDER 9
  1 SETS OF ORDER 13
  1 SETS OF ORDER 15
-----
  8

```

Fig. 7. Teletype output during calculation of minimal path sets of the Dresden-3 fault tree.

```

TIESET OF DRES03
  4 -2 999 50 51
  4 -2 998 42 43
  4 -2 997 34 35
  4 -2 996 27 28
  4 -2 995 23 24
  4 -2 994 19 20
  4 -2 993 7 8
  4 -2 992 1 3
  4 -2 991 52 53
  4 -2 990 44 45
  4 -2 989 29 38
  4 -2 988 16 37
  4 -2 987 21 22
  4 -2 986 9 10
  4 -2 985 4 5
  4 -2 984 54 55
  4 -2 983 46 47
  4 -2 982 39 989
  4 -2 981 32 33
  4 -2 980 11 12
  4 -2 979 6 13
  4 -2 978 56 57
  4 -2 977 48 49
  4 -2 976 40 41
  4 -2 975 25 26
  4 -2 974 986 993
  4 -2 973 14 15
  4 -2 972 978 984
  4 -2 971 977 983
  4 -2 970 982 996
  4 -2 969 16 973
  4 -2 968 972 991
  4 -2 967 971 990
  4 -2 966 969 979
  4 -2 965 968 999
  4 -2 964 967 998
  4 -2 963 966 985
  4 -2 962 963 992
  4 -2 961 18 30
  4 -2 960 31 961
-959
  2 970 975
  2 970 976
  2 987 995
  2 988 995
  4 2 17 962 994
  4 2 960 962 997
  4 2 974 980 994
  4 2 974 981 997

```

Fig. 8. Minimal path sets of the Dresden-3 fault tree.


```

HPIS 1000
+1000 310011002100310041005
+1012 4 31 32 33 34
+1004 4 35 36 37 38
X1001 210121004
+1020 5 99 101 102 105 106
+1019 4 107 108 110 111
X1010 210201019
+1062 6 180 88 89 90 91 97
+1063 9 92 93 94 95 96 97 98 192 181
X1061 210621063
+1014 31061 17 18
+1009 3101310531014
+1005 310091046 4
+1002 41005 1 2 3
+1015 5 69 70 71 72 188
+1016 5 73 74 75 76 189
X1010 210151016
+1006 61010 5 6 7 8 9
+1007 3 13 15 16
+1017 6 77 79 80 81 78 189
+1018 6 82 84 85 86 83 188
X1011 210171018
+1008 41011 10 11 12
+1003 3100610071008
+1044 6 61 62 63 64 185 191
+1045 6 65 66 67 68 186 190
X1040 210441045
X1041 2 59 60
+1017 210401041
+1042 4 123 134 185 191
+1043 4 135 136 190 186
X1028 210421043
+1039 12 19 20 21 22 23 24 25 26 27 28 29 30
+1016 3103710381039
+1049 7 39 40 41 42 43 183 189
+1050 7 44 45 46 47 48 184 188
X1047 210491050
+1051 7 49 50 51 52 53 183 189
+1052 7 54 55 56 57 58 184 188
X1048 210511052
+1046 210471048
+1058 5 115 116 117 118 119 181
+1057 21060 114
X1056 210571058
+1054 41056 112 113 192
+1060 3 126 127 187
+1059 31060 124 125
+1055 51059 120 121 122 123
X1053 210551054
+1064 101070 14 100 102 104 109 129 130 131 132
+1070 7 144 146 147 148 177 178 179
+1034 101071 142 137 143 138 139 149 150 151 152
+1071 10 145 140 153 154 155 141 156 157 158 159
X1032 210351064
+1026 21032 128
+1027 51034 198 196 192 193
X1022 210271026
+1028 21035 198
+1029 3 192 1931033
X1023 210281029
X1033 210341064
X1024 2 1971033
X1030 210341035
+1031 31064 198 199
X1025 210301031
+1021 41022102310241025
+1025 111072 160 161 162 163 164 165 166 167 168 169
+1072 9 170 171 172 173 174 175 176 194 195

```

Fig. 9. Input data for the HPIS fault tree.

CHECK OF INPUT DATA FOR : HPIS (PRIMAL)

GATE 1000 OCCURS ON LEFT SIDE BUT NOT ON RIGHT

NO OF DIFFERENT OR - GATES = 49

NO OF DIFFERENT AND - GATES = 19

TOTAL NO OF DIFFERENT GATES = 68

NO OF DIFFERENT EVENTS = 159

EVENTS	1	2	3	4	5	6	7	8	9	10	11	12
REPLICATION	1	1	1	1	1	1	1	1	1	1	1	1
EVENTS	13	14	15	16	17	18	19	20	21	22	23	24
REPLICATION	1	4	1	1	1	1	1	1	1	1	1	1
EVENTS	25	26	27	28	29	30	31	32	33	34	35	36
REPLICATION	1	1	1	1	1	1	1	1	1	1	1	1
EVENTS	37	38	39	40	41	42	43	44	45	46	47	48
REPLICATION	1	1	1	1	1	1	1	1	1	1	1	1
EVENTS	49	50	51	52	53	54	55	56	57	58	59	60
REPLICATION	1	1	1	1	1	1	1	1	1	1	1	1
EVENTS	61	62	63	64	65	66	67	68	69	70	71	72
REPLICATION	1	1	1	1	1	1	1	1	1	1	1	1
EVENTS	73	74	75	76	77	78	79	80	81	82	83	84
REPLICATION	1	1	1	1	1	1	1	1	1	1	1	1
EVENTS	85	86	87	88	89	90	91	92	93	94	95	96
REPLICATION	1	1	1	1	1	1	1	1	1	1	1	1
EVENTS	97	98	99	100	101	102	103	104	105	106	107	108
REPLICATION	1	1	1	4	1	4	1	4	1	1	1	1
EVENTS	109	110	111	112	113	114	115	116	117	118	119	120
REPLICATION	4	1	1	1	1	1	1	1	1	1	1	1
EVENTS	121	122	123	124	125	126	127	128	129	130	131	132
REPLICATION	1	1	1	1	1	2	2	1	4	4	4	4
EVENTS	133	134	135	136	137	138	139	140	141	142	143	144
REPLICATION	1	1	1	1	4	4	4	4	4	4	4	4
EVENTS	145	146	147	148	149	150	151	152	153	154	155	156
REPLICATION	4	4	4	4	4	4	4	4	4	4	4	4
EVENTS	157	158	159	160	161	162	163	164	165	166	167	168
REPLICATION	4	4	4	3	3	3	3	3	3	3	3	3
EVENTS	169	170	171	172	173	174	175	176	177	178	179	180
REPLICATION	3	3	3	3	3	3	3	3	4	4	4	1
EVENTS	181	182	183	184	185	186	187	188	189	190	191	192
REPLICATION	1	1	2	2	2	2	2	4	4	2	2	4
EVENTS	193	194	195	196	197	198	199					
REPLICATION	2	3	3	1	1	3	1					

Fig. 10. TREECH output for the HPIS fault tree.

GATE	BICS	MAX LENGTH	REPLICATION
1000	20311	3	1
1001	16	2	1
1002	421	3	1
1003	72	2	1
1004	4	1	1
1005	418	3	1
1006	38	2	1
1007	3	1	1
1008	39	2	1
1009	319	3	1
1010	23	2	1
1011	36	2	1
1012	4	1	1
1013	20	2	1
1014	56	2	1
1015	5	1	1
1016	5	1	1
1017	6	1	1
1018	6	1	1
1019	4	1	1
1020	5	1	1
1021	19917	3	1
1022	7015	3	1
1023	6120	3	1
1024	304	3	1
1025	6498	3	1
1026	305	2	1
1027	23	1	1
1028	20	1	1
1029	306	2	1
1030	361	2	1
1031	18	1	1
1032	304	2	1
1033	304	2	2
1034	19	1	2
1035	19	1	2
1036	65	2	1
1037	37	2	1
1038	16	2	1
1039	12	1	1
1040	36	2	1
1041	1	2	1
1042	4	1	1
1043	4	1	1
1044	6	1	1
1045	6	1	1
1046	98	2	1
1047	49	2	1
1048	49	2	1
1049	7	1	1
1050	7	1	1
1051	7	1	1
1052	7	1	1
1053	241	1	1
1054	27	2	1
1055	9	1	1
1056	24	2	1
1057	4	1	1
1058	6	1	1
1059	5	1	1
1060	3	1	2
1061	54	2	1
1062	6	1	1
1063	9	1	1
1064	16	1	2
1070	7	1	1
1071	10	1	1
1072	9	1	1

Fig. 10. TREECH output for the HPTS fault tree.

GATE	BICS	MAX LENGTH	REPLICATION
1000	248832	174	
1001	2	4	1
1002	48	43	1
1003	4	22	1
1004	1	4	1
1005	48	40	1
1006	2	10	1
1007	1	3	1
1008	2	9	1
1009	12	25	1
1010	2	5	1
1011	2	6	1
1012	1	4	1
1013	2	5	1
1014	2	11	1
1015	1	5	1
1016	1	5	1
1017	1	6	1
1018	1	6	1
1019	1	4	1
1020	1	5	1
1021	81	82	1
1022	3	23	1
1023	3	21	1
1024	3	19	1
1025	3	19	1
1026	2	20	1
1027	1	23	1
1028	1	20	1
1029	2	21	1
1030	2	19	1
1031	1	18	1
1032	2	19	1
1033	2	19	2
1034	1	19	3
1035	1	19	3
1036	8	23	1
1037	4	7	1
1038	2	4	1
1039	1	12	1
1040	2	6	1
1041	2	1	1
1042	1	4	1
1043	1	4	1
1044	1	6	1
1045	1	6	1
1046	4	14	1
1047	2	7	1
1048	2	7	1
1049	1	7	1
1050	1	7	1
1051	1	7	1
1052	1	7	1
1053	3	9	1
1054	2	9	1
1055	1	9	1
1056	2	6	1
1057	1	4	1
1058	1	6	1
1059	1	5	1
1060	1	3	2
1061	2	9	1
1062	1	6	1
1063	1	9	1
1064	1	16	3
1070	1	7	1
1071	1	10	1
1072	1	9	1

Fig. 11. TREECH output for the Dual of the HPIS fault tree.

```
R CUTSET
CUTSET OR TIESET: CUTSET
CUTSET OF:
FILE DSK0: HPIS
SYSTEM: HPIS
HIGHEST ORDER WANTED = 999
TOP GATE 1000
FACTORIZE
FACTORIZE
FACTORIZE
EVALUATE
MINIMIZE
MINIMIZE
OVERFLOW
REDUCE
OUTPUT
```

RESULT OF HPIS

REDUCED CUTSET:

```
1. SETS OF ORDER 1
43. SETS OF ORDER 2
8. SETS OF ORDER 3
```

52

EVALUATED CUTSET:

```
29 SETS OF ORDER 1
400. SETS OF ORDER 2
7750. SETS OF ORDER 3
```

8179

Fig. 12. Teletype output during calculation of minimal cut sets of the HPIS fault tree.

CUTSET OF HPIS

4	-1	999	11	12
4	-1	998	15	16
4	-1	997	99	101
4	-1	996	107	108
4	-1	995	87	88
4	-1	994	92	91
4	-1	991	62	70
4	-1	992	71	74
4	-1	991	77	78
4	-1	990	82	81
4	-1	989	81	82
4	-1	988	65	66
4	-2	987	59	60
4	-1	986	133	134
4	-1	985	135	136
4	-1	984	19	40
4	-1	983	44	45
4	-1	982	49	50
4	-1	981	54	55
4	-1	980	115	116
4	-1	979	112	113
4	-1	978	126	127
4	-1	977	14	100
4	-1	976	137	138
4	-1	975	160	161
4	-1	974	1	2
4	-1	973	33	34
4	-1	972	37	38
4	-1	971	103	105
4	-1	970	110	111
4	-1	969	89	90
4	-1	968	94	95
4	-1	967	71	72
4	-1	966	75	76
4	-1	965	79	80
4	-1	964	84	85
4	-1	963	63	64
4	-1	962	67	68
4	-1	961	185	191
4	-1	960	186	190
4	-1	959	41	42
4	-1	958	46	47
4	-1	957	51	52
4	-1	956	56	57
4	-1	955	117	118
4	-1	954	187	978
4	-1	953	102	104
4	-1	952	119	140
4	-1	951	162	163
4	-1	950	3	4
4	-1	949	973	999
4	-1	948	972	998
4	-1	947	106	971
4	-1	946	970	996
4	-1	945	91	100
4	-1	944	96	97
4	-1	943	967	993
4	-1	942	966	992
4	-1	941	81	965
4	-1	940	86	964
4	-1	939	963	989
4	-1	938	962	988
4	-1	937	43	959
4	-1	936	48	958
4	-1	935	53	957

4	-1	934	58	956
4	-1	933	119	181
4	-1	932	120	121
4	-1	931	109	129
4	-1	930	141	142
4	-1	929	164	165
4	-1	928	5	6
4	-1	927	947	997
4	-1	926	945	969
4	-1	925	98	182
4	-1	924	941	991
4	-1	923	940	990
4	-1	922	937	984
4	-1	921	936	983
4	-1	920	935	982
4	-1	919	934	981
4	-1	918	933	955
4	-1	917	122	123
4	-1	916	130	131
4	-1	915	143	145
4	-1	914	166	167
4	-1	913	7	8
4	-1	912	926	995
4	-1	911	925	944
4	-1	910	918	980
4	-1	909	124	125
4	-1	908	132	144
4	-1	907	149	150
4	-1	906	168	169
4	-1	905	9	10
4	-1	904	911	968
4	-1	903	909	917
4	-1	902	146	147
4	-1	901	151	152
4	-1	900	170	171
4	-1	899	11	12
4	-1	898	904	994
4	-1	897	903	932
4	-1	896	148	177
4	-1	895	153	154
4	-1	894	172	173
4	-1	893	172	173
4	-1	892	13	15
4	-1	891	178	179
4	-1	890	178	179
4	-1	889	155	156
4	-1	888	155	156
4	-1	887	174	175
4	-2	886	948	949
4	-2	885	927	946
4	-1	884	16	17
4	-1	883	891	896
4	-1	882	157	158
4	-1	881	176	194
4	-1	880	18	19
4	-1	879	883	902
4	-1	878	159	882
4	-1	877	195	881
4	-1	876	20	21
4	-1	875	879	908
4	-1	874	878	889
4	-1	873	877	887
4	-1	872	22	23
4	-1	871	875	916
4	-1	870	874	895
4	-1	869	873	894

Fig. 13. Result file for the HPIS fault tree.

```

4 -1 868 24 25
4 -1 867 871 931
4 -1 866 870 901
4 -1 865 869 900
4 -1 864 26 27
4 -1 863 867 953
4 -1 862 866 907
4 -1 861 865 906
4 -1 860 23 29
4 -1 859 863 977
4 -1 858 862 915
4 -1 857 861 914
4 -1 856 30 860
4 -1 855 858 930
4 -1 854 857 929
4 -1 853 856 864
4 -1 852 855 952
4 -1 851 854 951
4 -1 850 853 868
4 -1 849 852 976
4 -1 848 851 975
4 -1 847 850 872
4 -1 846 847 876
4 -1 845 846 880
4 -1 844 845 884
4 -1 843 844 885
4 -1 842 843 886
4 -1 841 842 892
4 -1 840 841 899
4 -1 839 840 905
4 -1 838 839 913
4 -1 837 838 928
4 -1 836 837 950
4 -1 835 836 974
4 -1 834 835 987
-833
1 834
2 128 192
2 128 193
2 128 196
2 128 198
2 128 849
2 183 184
2 183 188
2 183 919
2 183 921
2 184 189
2 184 920
2 184 922
2 188 189
2 188 920
2 188 922
2 188 924
2 188 942
2 189 919
2 189 921
2 189 923
2 189 943
2 192 198
2 192 848
2 192 897
2 192 912
2 192 954
2 193 198
2 193 848
2 897 979
2 898 912
2 910 954
2 919 920
2 921 922
2 923 924
2 938 939
2 938 961
2 939 960
2 942 943
2 954 979
2 960 961
2 960 986
2 961 985
2 985 986
3 114 897 910
3 196 848 859
3 197 849 859
3 198 848 849
3 198 848 859
3 198 849 859
3 199 848 849
3 848 849 859

```

Fig. 13. Result file for the HPIS fault tree.

```

000000
1.1.2.1.10
2.1.2.0.1.15
3.1.2.9.009.48
4.1.2.9.009.48
5.1.2.100.1.4
6.1.2.1.5
7.1.2.1.10
8.1.2.9.009.48
9.1.2.9.009.48
10.1.2.1.5
11.1.2.1.5
12.1.2.5.8
13.1.2.1.5
14.1.2.9.009.48
15.1.2.9.009.48
16.1.2.1.5
17.1.2.5.8
18.1.2.1.5
19.1.2.5.8
20.1.2.5.8
21.1.2.5.8
22.1.2.10.1
23.1.2.10.100
24.1.2.1.5
25.1.2.10.1
26.1.2.5.8
27.1.2.9.009.48
28.1.2.9.009.48
29.1.2.1.5
30.1.2.5.8
31.1.2.10.1
32.1.2.5.8
33.1.2.10.1
34.1.2.5.8
35.1.2.5.1
36.1.2.0.5.8
37.1.2.10.1
38.1.2.1.10
39.1.2.10.10
40.1.2.5.8
41.1.2.10.1
42.1.2.5.8
43.1.2.10.1
44.1.2.1.5
45.1.2.9.009.48
46.1.2.9.009.48
47.1.2.1.5
48.1.2.5.8
49.1.2.10.1
50.1.2.5.8
51.1.2.10.1
52.1.2.1.5
53.1.2.9.009.48
54.1.2.9.009.48
55.1.2.1.5
56.1.2.5.8
57.1.2.10.1
0

```

Fig. 14. Failure data for the components of the Dresden-3 system.

UNAVAILABILITY CALCULATION FOR FAULT TREE: DRESO3
CALCULATION BASED ON CUTSET

NO OF MINIMAL SETS = 48

TIME	UNAVAILABILITY	
168.000	0.91181E-09	0.91177E-09
336.000	0.13236E-07	0.13233E-07
504.000	0.64278E-07	0.64253E-07
672.000	0.19802E-06	0.19788E-06
840.000	0.47404E-06	0.47355E-06
1008.000	0.96711E-06	0.96568E-06
1176.000	0.17660E-05	0.17625E-05
1344.000	0.29737E-05	0.29660E-05
1512.000	0.47047E-05	0.46894E-05
1680.000	0.70868E-05	0.70585E-05
3360.000	0.10227E-03	0.10070E-03
5040.000	0.47188E-03	0.45615E-03
6720.000	0.13669E-02	0.12880E-02
8400.000	0.30724E-02	0.28014E-02
10079.937	0.58895E-02	0.51565E-02
11760.002	0.10125E-01	0.84411E-02
13440.001	0.16087E-01	0.12650E-01
15119.999	0.24080E-01	0.17669E-01
16799.998	0.34408E-01	0.23258E-01

Fig. 15. Unavailability of the Dresden-3 system. Non-repairable case.
Two inclusion-exclusion terms.

UNAVAILABILITY CALCULATION FOR FAULT TREE DRESO3
CALCULATION BASED ON CUTSET

NO OF MINIMAL SETS = 48

TIME	UNAVAILABILITY	
0.000	0.00000E+00	0.00000E+00
200.000	0.42631E-10	0.42631E-10
400.000	0.66005E-10	0.66005E-10
600.000	0.65433E-10	0.65433E-10
800.000	0.65638E-10	0.65638E-10

Fig. 16. Unavailability of the Dresden-3 system. Repairable case.
Two inclusion-exclusion terms.

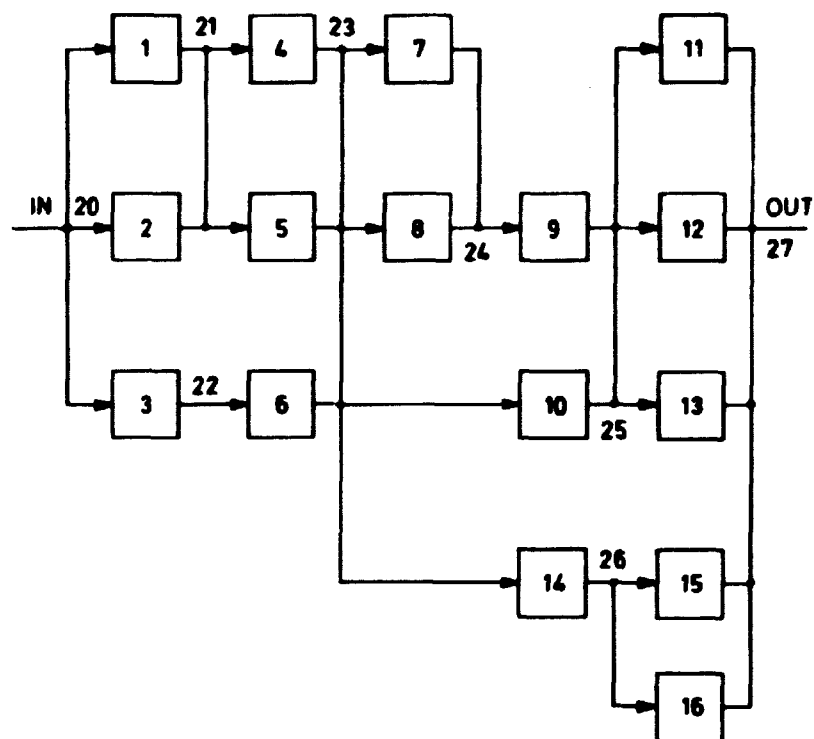


Fig. 17. Uni-directional network (taken from reference 22) used to illustrate the TIENET program.

```

NBBEX2
-1, 20, 21
-2, 20, 21
-3, 20, 22
-4, 21, 23
-5, 21, 23
-6, 22, 23
-7, 23, 24
-8, 23, 24
-9, 24, 25
-10, 23, 25
-11, 25, 27
-12, 25, 27
-13, 25, 27
-14, 23, 26
-15, 26, 27
-16, 26, 27
0

```

Fig. 18. Input data file to TIENET. Data corresponds to the network in fig. 17.

COMPONENT LIST

	COMPO - NENT	INPUT NODE	OUTPUT NODE	NEXT COMPONENT DESCRIPTION
--	-----------------	---------------	----------------	----------------------------------

NODE LIST

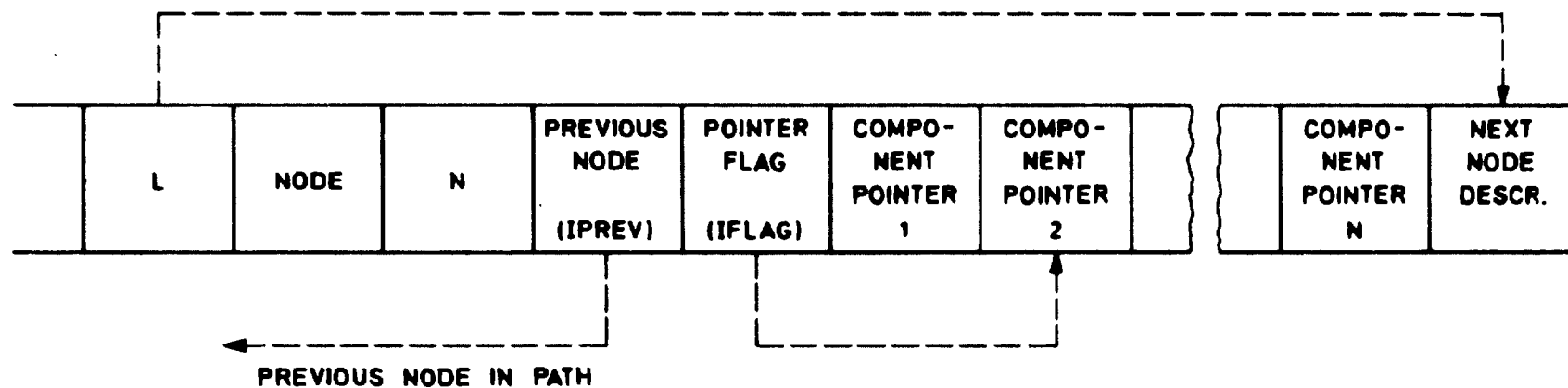


Fig. 19. Internal Lists in TIENET.

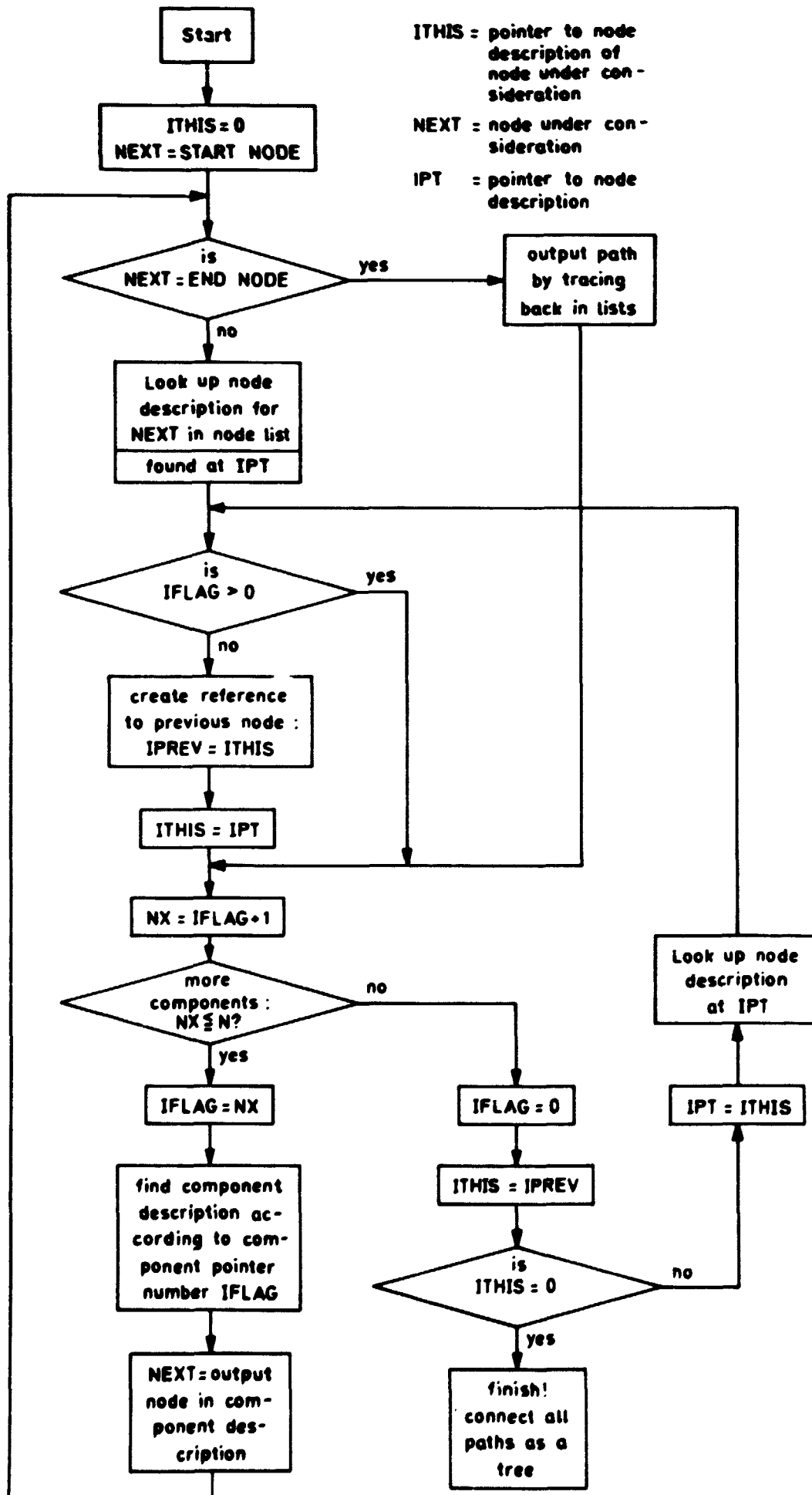


Fig. 20. Flowchart for TIENET.

```

NBBEX2
X1000 11001
+1002 5 1 4 7 9 11
+1003 5 1 4 7 9 12
+1004 5 1 4 7 9 13
+1005 5 1 4 8 9 11
+1006 5 1 4 8 9 12
+1007 5 1 4 8 9 13
+1008 4 1 4 10 11
+1009 4 1 4 10 12
+1010 4 1 4 10 13
+1011 4 1 4 14 15
+1012 4 1 4 14 16
+1013 5 1 5 7 9 11
+1014 5 1 5 7 9 12
+1015 5 1 5 7 9 13
+1016 5 1 5 8 9 11
+1017 5 1 5 8 9 12
+1018 5 1 5 8 9 13
+1019 4 1 5 10 11
+1020 4 1 5 10 12
+1021 4 1 5 10 13
+1022 4 1 5 14 15
+1023 4 1 5 14 16
+1024 5 2 4 7 9 11
+1025 5 2 4 7 9 12
+1026 5 2 4 7 9 13
+1027 5 2 4 8 9 11
+1028 5 2 4 8 9 12
+1029 5 2 4 8 9 13
+1030 4 2 4 10 11
+1031 4 2 4 10 12
+1032 4 2 4 10 13
+1033 4 2 4 14 15
+1034 4 2 4 14 16
+1035 5 2 5 7 9 11
+1036 5 2 5 7 9 12
+1037 5 2 5 7 9 13
+1038 5 2 5 8 9 11
+1039 5 2 5 8 9 12
+1040 5 2 5 8 9 13
+1041 4 2 5 10 11
+1042 4 2 5 10 12
+1043 4 2 5 10 13
+1044 4 2 5 14 15
+1045 4 2 5 14 16
+1046 5 3 6 7 9 11
+1047 5 3 6 7 9 12
+1048 5 3 6 7 9 13
+1049 5 3 6 8 9 11
+1050 5 3 6 8 9 12
+1051 5 3 6 8 9 13
+1052 4 3 6 10 11
+1053 4 3 6 10 12
+1054 4 3 6 10 13
+1055 4 3 6 14 15
+1056 4 3 6 14 16
X1001 101002100310041005100610071008100910101057
X1057 101011101210131014101510161017101810191058
X1058 101020102110221023102410251026102710281059
X1059 101029103010311032103310341035103610371060
X1060 101038103910401041104210431044104510461061
X1061 101047104810491050105110521053105410551056
$

```

Fig. 21. Output file from TIENET. The data corresponds to the network in fig. 17.

R CUTSET					
CUTSET OR TIESET: TIESET					
TIESET OF:					
FILE DSK0: P20127					
SYSTEM: NBBEX2					
HIGHEST ORDER WANTED = 999					
TOP GATE:					
GATE: 1000 SELECTED AS TOP					
FACTORIZE					
EVALUATE					
MINIMIZE					
OVERFLOW					
REDUCE					
OUTPUT					
RESULT OF NBBEX2					
REDUCED TIESET:					
5 SETS OF ORDER 3					
26 SETS OF ORDER 4					
24 SETS OF ORDER 5					

55.					
EVALUATED TIESET:					
25 SETS OF ORDER 4					
30 SETS OF ORDER 5					

55.					

TIESET OF NBBEX2	4	-2	999	3	6
-998	3	10	11	999	
	3	10	12	999	
	3	10	13	999	
	3	14	15	999	
	3	14	16	999	
	4	1	4	10	11
	4	1	4	10	12
	4	1	4	10	13
	4	1	4	14	15
	4	1	4	14	16
	4	1	5	10	11
	4	1	5	10	12
	4	1	5	10	13
	4	1	5	14	15
	4	1	5	14	16
	4	2	4	10	11
	4	2	4	10	12
	4	2	4	10	13
	4	2	4	14	15
	4	2	4	14	16
	4	2	5	10	11
	4	2	5	10	12
	4	2	5	10	13
	4	2	5	14	15
	4	2	5	14	16
	4	7	9	11	999
	4	7	9	12	999
	4	7	9	13	999
	4	8	9	11	999
	4	8	9	12	999
	4	8	9	13	999
	5	1	4	7	9
	5	1	4	7	9
	5	1	4	7	9
	5	1	4	8	9
	5	1	4	8	9
	5	1	4	8	9
	5	1	4	8	9
	5	1	5	7	9
	5	1	5	7	9
	5	1	5	7	9
	5	1	5	8	9
	5	1	5	8	9
	5	1	5	8	9
	5	2	4	7	9
	5	2	4	7	9
	5	2	4	7	9
	5	2	4	8	9
	5	2	4	8	9
	5	2	4	8	9
	5	2	5	7	9
	5	2	5	7	9
	5	2	5	7	9
	5	2	5	8	9
	5	2	5	8	9
	5	2	5	8	9

Fig. 23. Minimal path sets for the network in fig. 17.

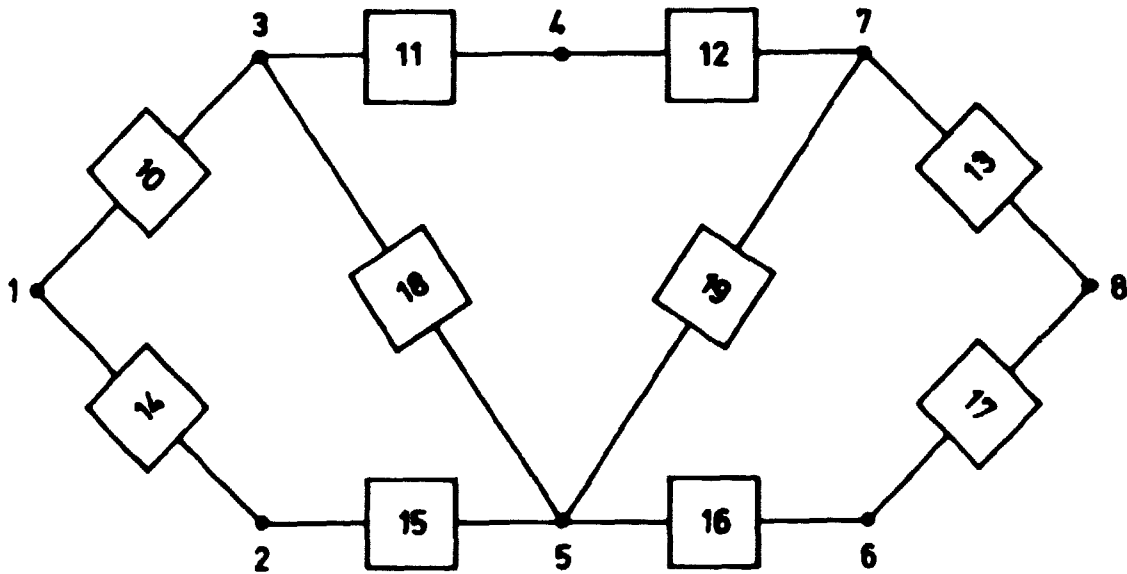


Fig. 24. Bi-directional network (taken from reference 20) used to illustrate the TIENET program.

TYPE JBF IG1. DA

```
JBF IG1
10. 1. 3
11. 3. 4
12. 4. 7
13. 7. 8
14. 1. 2
15. 2. 5
16. 5. 6
17. 6. 8
18. 3. 5
19. 5. 7
0
```

Fig. 25. TIENET input data for the network in fig. 24.


```

R TIENET
NETWORK PATHS
OUTPUT NODES, COMPONENTS OR BOTH? NODES
NETWORK FILE
FILE DSK0 JBFIG1
CALCULATE PATHS FROM NODE 1
TO NODE 8
OUTPUT ON
FILE DSK0 NB1T08

R TIENET
NETWORK PATHS
OUTPUT NODES, COMPONENTS OR BOTH? COMPONENTS
NETWORK FILE
FILE DSK0 JBFIG1
CALCULATE PATHS FROM NODE 1
TO NODE 8
OUTPUT ON
FILE DSK0 CB1T08

R TIENET
NETWORK PATHS
OUTPUT NODES, COMPONENTS OR BOTH? BOTH
NETWORK FILE
FILE DSK0 JBFIG1
CALCULATE PATHS FROM NODE 1
TO NODE 8
OUTPUT ON
FILE DSK0 BB1T08

```

Fig. 26. Teletype output during three runs of TIENET for the network in fig. 24.

```

R CUTSET
CUTSET OR TIESET. CUTSET
CUTSET OF
FILE DSK0 NB1T08
SYSTEM: JBFIG1
HIGHEST ORDER WANTED = 999
TOP GATE:
GATE: 1000 SELECTED AS TOP
FACTORIZE
EVALUATE
MINIMIZE
MINIMIZE
OVERFLOW
REDUCE
OUTPUT

```

RESULT OF JBFIG1

```

REDUCED CUTSET:
1. SETS OF ORDER 1
5. SETS OF ORDER 2
-----
6.

```

```

EVALUATED CUTSET:
2. SETS OF ORDER 1
5. SETS OF ORDER 2
-----
7.

```

```

R CUTEV
EVALUATE COMPLEX EVENTS
TYPE EVAL. DA

```

```

CUTSET OF JBFIG1
1      8
1      1
2      2      3
2      3      5
2      4      5
2      5      7
2      6      7

```

Fig. 27. Minimal cut sets of the network in fig. 24. Nodes only.

R CUTSET
 CUTSET OR TIESET: CUTSET
 CUTSET OF:
 FILE DSK0, C01103
 SYSTEM: JBF1G1
 HIGHEST ORDER WANTED = 999
 TOP GATE:
 GATE: 1000 SELECTED AS TOP
 FACTORIZE
 EVALUATE
 MINIMIZE
 MINIMIZE
 OVERFLOW
 REDUCE
 OUTPUT

RESULT OF JBF1G1

REDUCED CUTSET:
 2. SETS OF ORDER 2
 2. SETS OF ORDER 3
 2. SETS OF ORDER 4

 6.

EVALUATED CUTSET:
 4. SETS OF ORDER 2
 8. SETS OF ORDER 3
 4. SETS OF ORDER 4

 16.

R CUTEV
 EVALUATE COMPLEX EVENTS
 TYPE EVAL. DA

CUTSET OF JBF1G1
 2 10 15
 2 10 14
 2 13 17
 2 13 16
 3 12 15 18
 3 12 14 18
 3 11 15 18
 3 11 14 18
 3 12 17 19
 3 12 16 19
 3 11 17 19
 3 11 16 19
 4 10 17 18 19
 4 10 16 18 19
 4 13 15 18 19
 4 13 14 18 19

Fig. 28. Minimal cut sets of the network in fig. 24. Components only.

R CUTSET	TYPE EVAL. PA
CUTSET OR TIESET: CUTSET	
CUTSET OF:	
FILE DSK: B01108	
SYSTEM: JBF101	CUTSET OF JBF101
HIGHEST ORDER WANTED = 999	1 8
TOP GATE:	1 1
GATE: 1000 SELECTED AS TOP	2 3 5
FACTORIZE	2 3 14
EVALUATE	2 3 15
MINIMIZE	2 2 3
MINIMIZE	2 5 7
OVERFLOW	2 5 10
REDUCE	2 5 13
OUTPUT	2 5 11
	2 5 12
	2 4 5
RESULT OF JBF101	2 7 16
	2 7 17
REDUCED CUTSET:	2 6 7
1. SETS OF ORDER 1	2 10 14
9. SETS OF ORDER 2	2 10 15
4. SETS OF ORDER 3	2 2 10
2. SETS OF ORDER 4	2 13 16
-----	2 13 17
16.	2 6 13
	3 3 16 19
EVALUATED CUTSET:	3 3 17 19
2. SETS OF ORDER 1	3 3 6 19
19. SETS OF ORDER 2	3 7 14 18
24. SETS OF ORDER 3	3 7 15 18
6. SETS OF ORDER 4	3 2 7 18
-----	3 11 14 18
51.	3 11 15 18
	3 2 11 18
R CUTEV	3 12 14 18
EVALUATE COMPLEX EVENTS	3 4 14 18
	3 12 15 18
	3 4 15 18
	3 2 12 18
	3 2 4 18
	3 11 16 19
	3 11 17 19
	3 6 11 19
	3 12 16 19
	3 4 16 19
	3 12 17 19
	3 4 17 19
	3 6 12 19
	3 4 6 19
	4 10 16 18 19
	4 10 17 18 19
	4 6 18 18 19
	4 13 14 18 19
	4 13 15 18 19
	4 2 13 18 19

Fig. 29. Minimal cut sets of the network in fig. 24. Nodes and components.

```

R CUTSET
CUTSET OR TIESET: TIESET
TIESET OF:
  FILE DSK0: C01100
  SYSTEM: JBF101
  HIGHEST ORDER WANTED = 999
  TOP GATE:
  GATE: 1000 SELECTED AS TOP
  FACTORIZE
  EVALUATE
  MINIMIZE
  OVERFLOW
  REDUCE
  OUTPUT

```

RESULT OF JBF101

```

REDUCED TIESET:
  1. SETS OF ORDER 2
  3. SETS OF ORDER 3
  3. SETS OF ORDER 4
-----
  7.

```

```

EVALUATED TIESET:
  5. SETS OF ORDER 4
  2. SETS OF ORDER 6
-----
  7.

```

```

R CUTEV
EVALUATE COMPLEX EVENTS

```

TYPE EVAL DA

```

TIESET OF JBF101
  4  14  15  16  17
  4  10  11  12  13
  4  10  16  17  18
  4  13  14  15  19
  4  10  13  18  19
  6  10  11  12  16  17  19
  6  11  12  13  14  15  18

```

Fig. 30. Minimal path sets of the network in fig. 24. Components only.